METR 5123, Advanced Atmospheric Dynamics II
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## REVIEW OF SURFACE GRAVITY WAVES

First, we'll review some notation and concepts that will be applicable to many kinds of waves (not just surface gravity waves).

Often we'll work w/ waves of the form:
some flow property $\sim a \sin \left[\frac{2 \pi}{\lambda}(x-c t)\right]$ or $a \cos \left[\frac{2 \pi}{\lambda}(x-c t)\right]$
a is amplitude
$\frac{2 \pi}{\lambda}(x-c t)$ is phase of wave
$\lambda$ is wavelength
c is phase speed
Why consider waves of this form?
-- Many waves in atmosphere "look" like sines or cosines.
-- Many waves approximately satisfy linear const coeff odes and pdes that permit sin and cos solns. Can use Fourier analysis to get solns of complicated problems by summing sin and cos solns of various amplitudes and wavelengths.

A closer look at wave parameters:
phase: $\frac{2 \pi}{\lambda}(\mathrm{x}-\mathrm{ct})$
Wave repeats itself when phase changes by $2 \pi$. So, at a fixed moment in time, phase changes by $2 \pi$ when x changes by $\lambda$. Hence the name wavelength for $\lambda$.
$\mathrm{k} \equiv \frac{2 \pi}{\lambda}$ is wavenumber, \# waves in (dimensional) length of $2 \pi$.
e.g., if $\lambda=\pi$ (meters) then there are 2 waves in $2 \pi$ meters.
$\mathrm{k}=\frac{2 \pi}{\pi \mathrm{~m}}=2 \mathrm{~m}^{-1}$.

Think: long waves --> small k short waves --> big k

At a fixed point, phase changes by $2 \pi$ when time changes by $\frac{\lambda}{\mathrm{c}}$ So wave period is: $\mathrm{T} \equiv \frac{\lambda}{\mathrm{c}}$.
$v \equiv \frac{1}{T}$ is $\underline{\text { frequency }, ~ \# ~ o f ~ o s c i l l a t i o n s ~ p e r ~ u n i t ~ t i m e ~}$
$\omega \equiv \frac{2 \pi}{T}=2 \pi \nu$ is circular (or radian) frequency.
Since $T=\frac{\lambda}{c} \rightarrow \omega=2 \pi \frac{c}{\lambda}=\mathrm{kc}$
$\therefore \quad \mathrm{c}=\frac{\omega}{\mathrm{k}}$
alternate expressions:

$$
\begin{aligned}
& \sin \frac{2 \pi}{\lambda}(x-c t) \\
& \sin [k(x-c t)] \\
& \sin (k x-\omega t)
\end{aligned}
$$

Motion of crests/troughts is motion of a geometric pattern. Fluid does not generally move with the wave pattern, e.g. Rossby waves, e.g., ocean waves might propagate toward shore at 20 $\mathrm{m} / \mathrm{s}$, but fluid moves toward and away from shore at $\sim 1 \mathrm{~m} / \mathrm{s}$.

## Surface gravity waves

Consider 2-D motion in the $\mathrm{x}-\mathrm{z}$ plane of a liquid $\mathrm{w} / \mathrm{a}$ free surface (e.g. air/sea interface) [a pool of cold air underlying warm air is similar but more complicated]

-- assume disturbance is "infinitesimal", i.e., a is so small that:

$$
\begin{array}{ll} 
& \mathrm{a} \ll \mathrm{H}(\mathrm{a} / \mathrm{H} \ll 1) \\
\text { and } \quad & \mathrm{a} \ll \lambda(\mathrm{a} / \lambda \ll 1)
\end{array}
$$

Because of this, nonlinear accel ${ }^{\mathrm{n}}$ terms are very small compared to local derivs (products of small quantities are really small)
-- neglect friction
-- assume T << rotation period of earth, or equivalently $\omega$ >> f
$\therefore$ can safely neglect Coriolis force.
-- assume fluid was initially at rest (so irrotational) and waves created irrotationally. So from Kelvin's $\mathrm{Th}^{\mathrm{m}}$, the flow will always be irrot. So $\vec{\omega}(\mathrm{t})=0$

$$
\therefore \quad \overrightarrow{\mathrm{u}}(\mathrm{t})=\nabla \phi(\mathrm{t})
$$

-- assume flow is incompressible, $\nabla \cdot \overrightarrow{\mathrm{u}}=0$
Substituting in $\overrightarrow{\mathrm{u}}=\nabla \phi$ we get:

$$
\nabla \cdot \nabla \phi=0
$$

$\therefore \nabla^{2} \phi=0$ Laplace's eqn.

$$
\frac{\partial^{2} \phi}{\partial \mathrm{x}^{2}}+\frac{\partial^{2} \phi}{\partial \mathrm{z}^{2}}=0
$$

Need b.c.s to solve it. At bottom: impermeability condn:

$\therefore \frac{\partial \phi}{\partial \mathrm{z}}=0$ at $\mathrm{z}=-\mathrm{H}$
On top (free surface): a kinematic b.c. and a dynamic b.c.
Top Kinematic b.c.: A fluid element on free sfc remains on that sfc no matter how sfc moves or deforms. $\therefore \mathrm{z}_{\text {parcel on } \mathrm{sfc}}=\eta$
$\therefore \mathrm{w}_{\text {parcel on sfc }}=\frac{\mathrm{D}}{\mathrm{Dt}} \mathrm{z}_{\text {parcel on sfc }}=\frac{\mathrm{D} \eta}{\mathrm{Dt}}=\frac{\partial \eta}{\partial \mathrm{t}}+\mathrm{u} \frac{\partial \eta}{\partial \mathrm{x}}$
$\therefore \quad \frac{\partial \phi}{\partial \mathrm{z}}=\frac{\partial \eta}{\partial \mathrm{t}}+\mathrm{u} \frac{\partial \eta}{\partial \mathrm{x}} \quad$ on $\mathrm{z}=\eta(\mathrm{x}, \mathrm{t})$
sfc moving upward:

$\partial \eta / \partial t>0 \therefore w>0$

Stationary sfc with $u>0$


For infinitesimal waves, neglect products of small quantities (nonlinear terms). Neglect u $\partial \eta / \partial x$.
$\therefore \frac{\partial \phi}{\partial z}=\frac{\partial \eta}{\partial t}$ on $\mathrm{z}=\eta(\mathrm{x}, \mathrm{t})$ [still nonlinear: $\eta$ is affected by flow]
Exapnd 1.h.s. in a Taylor series about $\mathrm{z}=0$ :
$\left.\frac{\partial \phi}{\partial z}\right|_{z=\eta}=\left.\frac{\partial \phi}{\partial z}\right|_{z=0}+\left.\frac{\partial}{\partial z}\left(\frac{\partial \phi}{\partial z}\right)\right|_{z=0} \eta+\ldots$

$\therefore \frac{\partial \phi}{\partial \mathrm{z}}=\frac{\partial \eta}{\partial \mathrm{t}}$ on $\mathrm{z}=0$ Linearized kinematic b.c. on free sfc.
[Neglected a nonlinear term and put b.c. at $\mathrm{z}=0$ instead of $\mathrm{z}=\eta$ ]
Dynamic b.c. on free surface: pressure is continuous across air/sea interface. So pressure on liquid side of interface $=$ atm pressure.


$$
\mathrm{p}(\mathrm{z}=\eta(\mathrm{x}, \mathrm{t}))=\mathrm{p}_{\mathrm{atm}}
$$

Translate this b.c. into a b.c. on $\phi$, using Bernoulli's eqn for unsteady, irrot flow:

$$
\frac{\partial \phi}{\partial t}+\frac{q^{2}}{2}+\frac{p}{\rho}+g z=C \quad \text { (same const everywhere) }
$$

Apply it on free $\mathrm{sfc} \mathrm{z}=\eta$ (liquid side), $\mathrm{w} / \mathrm{p}=\mathrm{p}_{\text {atm }}$, and neglect $\mathrm{q}^{2}$ :

$$
\begin{aligned}
& \therefore \frac{\partial \phi}{\partial \mathrm{t}}+\frac{\mathrm{p}_{\mathrm{atm}}}{\rho}+\mathrm{g} \mathrm{\eta}=\mathrm{C} \\
& \therefore \frac{\partial \phi}{\partial \mathrm{t}}+\mathrm{g} \mathrm{\eta}=\left(\mathrm{C}-\frac{\mathrm{p}_{\mathrm{atm}}}{\rho}\right)=\mathrm{const}
\end{aligned}
$$

Set const $=0$. [Flow doesn't care about it. Equivalently, define $\phi_{\text {new }}=\phi_{\text {old }}+$ const t , and plug into above eqn. The const cancels out, but since $\overrightarrow{\mathrm{u}}=\nabla \phi$ and $\nabla \phi_{\text {new }}=\nabla \phi_{\text {old }}$, the flow is unchanged.]

$$
\therefore \underset{\frac{\partial \phi}{\downarrow t}}{\partial}+g \eta=0 \text { at } \mathrm{z}=\eta
$$

Expand it in a Taylor series in z about $\mathrm{z}=0$ :

$$
\left.\therefore \quad \frac{\partial \phi}{\partial t}\right|_{z=\eta}=\left.\frac{\partial \phi}{\partial t}\right|_{z=0}+\left.\frac{\partial}{\partial z}\left(\frac{\partial \phi}{\partial t}\right)\right|_{z=0} ^{\text {[neglect since } \eta \text { is small] }} \eta+\text { h.o.t. }
$$

$\therefore$ linearized dynamic free sfc b.c. is:

$$
\frac{\partial \phi}{\partial t}+g \eta=0 \quad \text { at } \mathrm{z}=0
$$

Want to solve $\frac{\partial^{2} \phi}{\partial \mathrm{x}^{2}}+\frac{\partial^{2} \phi}{\partial \mathrm{z}^{2}}=0$ subject to the above b.c.
Consider a "wavy" pattern for $\eta$ : $\eta=a \cos (k x-\omega t)$
From either top b.c., suspect $\phi \propto \sin (k x-\omega t) w / a z$ dependence.
Trial solution: $\phi=\mathrm{f}(\mathrm{z}) \sin (\mathrm{kx}-\omega \mathrm{t}) \quad$ [will it work?] Plug it into Laplace's eqn, get:

$$
-k^{2} f \sin (k x-\omega t)+\frac{d^{2} f}{d z^{2}} \sin (k x-\omega t)=0
$$

$$
\therefore \quad \frac{\mathrm{d}^{2} \mathrm{f}}{\mathrm{dz}}-\mathrm{k}^{2} \mathrm{f}=0 \quad \text { a } 2^{\text {nd }} \text { order linear const coeff ode }
$$

Trial sols for $\mathrm{f}: \mathrm{f}=\mathrm{e}^{\mathrm{mz}}$. Plug into ode, get:

$$
\mathrm{m}^{2}-\mathrm{k}^{2}=0, \therefore \mathrm{~m}=\mathrm{k} \text { or }-\mathrm{k}
$$

So general sol for $f$ is: $f=A e^{k z}+B e^{-k z}$ and so $\phi$ becomes:
(*) $\phi=\left(\mathrm{Ae}^{\mathrm{kz}}+\mathrm{Be}^{-\mathrm{kz}}\right) \sin (\mathrm{kx}-\omega \mathrm{t})$
Now use bic. to pin down A, B.
Lower kinematic bic. is

$$
\frac{\partial \phi}{\partial z}=0 \text { at } \mathrm{z}=-\mathrm{H} .
$$

Apply it in (*), get

$$
\begin{aligned}
& \left.\left(\mathrm{Ake}^{\mathrm{kz}}-\mathrm{kB} \mathrm{e}^{-\mathrm{kz}}\right)\right|_{\mathrm{z}=-\mathrm{H}} \sin (\mathrm{kx}-\omega \mathrm{t})=0 \\
\therefore & \mathrm{Ak} \mathrm{e}^{-\mathrm{kH}}-\mathrm{kB} \mathrm{e}^{\mathrm{kH}}=0
\end{aligned}
$$

$\therefore \mathrm{A}=\mathrm{Be}^{2 \mathrm{kH}}$

Top linearized kinematic b.c. is

$$
\frac{\partial \phi}{\partial z}=\frac{\partial \eta}{\partial t} \text { on } z=0 .
$$

Apply it in (*), get
$\left.\therefore\left(A \mathrm{Ae}^{\mathrm{kz}}-\mathrm{kBe}^{-\mathrm{kz}}\right)\right|_{\mathrm{z}=0} \sin (\mathrm{kx}-\omega \mathrm{t})=-\mathrm{a}(-\omega) \sin (\mathrm{kx}-\omega \mathrm{t})$

$$
\therefore \mathrm{k}(\mathrm{~A}-\mathrm{B})=\mathrm{a} \omega
$$

2 linear algebraic eqns for 2 unknowns, A, B. Solution is:

$$
\begin{aligned}
A & =\frac{a \omega}{k\left(e^{2 k H}-1\right)} e^{2 k H}, \quad B=\frac{a \omega}{k\left(e^{2 k H}-1\right)} \\
\therefore \quad \phi & =\frac{a \omega}{k\left(e^{2 k H}-1\right)}\left(e^{2 k H} e^{k z}+e^{-k z}\right) \sin (k x-\omega t)
\end{aligned}
$$

factor out $\mathrm{e}^{\mathrm{kH}}$ from top and bottom, and mult by $\frac{2}{2}$
$\therefore \quad \phi=\frac{\mathrm{a} \omega}{\mathrm{k}} \frac{2}{\mathrm{e}^{\mathrm{kH}}-\mathrm{e}^{-\mathrm{kH}}}\left(\frac{\mathrm{e}^{\mathrm{k}(\mathrm{z}+\mathrm{H})}+\mathrm{e}^{-\mathrm{k}(\mathrm{z}+\mathrm{H})}}{2}\right) \sin (\mathrm{kx}-\omega \mathrm{t})$
$\therefore \quad \phi=\frac{\mathrm{a} \omega}{\mathrm{k}} \frac{\cosh [\mathrm{k}(\mathrm{z}+\mathrm{H})]}{\sinh (\mathrm{kH})} \sin (\mathrm{kx}-\omega \mathrm{t})$
----- scratch paper, review of hyperbolic functions
here's how $\mathrm{e}^{\mathrm{x}}$ and $\mathrm{e}^{-\mathrm{x}}$ behave:



Now define $\cosh \equiv \frac{\mathrm{e}^{\mathrm{x}}+\mathrm{e}^{-\mathrm{x}}}{2}$, the average of $\mathrm{e}^{\mathrm{x}}$ and $\mathrm{e}^{-\mathrm{x}}$ :


Now define $\sinh \mathrm{x} \equiv \frac{\mathrm{e}^{\mathrm{x}}-\mathrm{e}^{-\mathrm{x}}}{2}$, the difference btw $\mathrm{e}^{\mathrm{x}}$ and $\mathrm{e}^{-\mathrm{x}}$ (divided by 2 ):
for $\mathrm{x} \ll-1$, behaves like $-\frac{1}{2} \mathrm{e}^{-\mathrm{x}}$

$\frac{d}{d x} \cosh x=\frac{1}{2} \frac{d}{d x}\left(e^{x}+e^{-x}\right)=\frac{1}{2}\left(e^{x}-e^{-x}\right)=\sinh x$
$\frac{d}{d x} \sinh x=\frac{1}{2} \frac{d}{d x}\left(e^{x}-e^{-x}\right)=\frac{1}{2}\left(e^{x}+e^{-x}\right)=\cosh x$

Now define $\tanh x \equiv \frac{\sinh x}{\cosh x}$

------------- end of scratch paper

$$
\mathrm{u}=\frac{\partial \phi}{\partial \mathrm{x}}=\mathrm{a} \omega \frac{\cosh [\mathrm{k}(\mathrm{z}+\mathrm{H})]}{\sinh (\mathrm{kH})} \cos (\mathrm{kx}-\omega \mathrm{t})
$$

$$
\mathrm{w}=\frac{\partial \phi}{\partial \mathrm{z}}=\mathrm{a} \omega \frac{\sinh [\mathrm{k}(\mathrm{z}+\mathrm{H})]}{\sinh (\mathrm{kH})} \sin (\mathrm{kx}-\omega \mathrm{t})
$$

Get p from linearized Bernoulli eqn:

$$
\begin{aligned}
\frac{\mathrm{p}}{\rho}= & \text { const }-\mathrm{gz}-\frac{\partial \phi}{\partial \mathrm{t}} \\
& =\text { const }-\mathrm{gz}+\frac{\mathrm{a} \omega^{2}}{\mathrm{k}} \frac{\cosh [\mathrm{k}(\mathrm{z}+\mathrm{H})]}{\sinh (\mathrm{kH})} \cos (\mathrm{kx}-\omega \mathrm{t})
\end{aligned}
$$

Now apply linearized dynamic b.c.: $\frac{\partial \phi}{\partial \mathrm{t}}+\mathrm{g} \mathrm{\eta}=0$ on $\mathrm{z}=0$

$$
\begin{aligned}
& \therefore \quad-\frac{\mathrm{a} \omega^{2}}{\mathrm{k}} \frac{\cosh (\mathrm{kH})}{\sinh (\mathrm{kH})} \cos (\mathrm{kx}-\omega \mathrm{t})+\mathrm{g} \mathrm{a} \cos (\mathrm{kx}-\omega \mathrm{t})=0 \\
& \omega^{2}=\mathrm{gk} \tanh (\mathrm{kH})
\end{aligned}
$$

$\therefore \omega=\sqrt{\mathrm{gk} \tanh (\mathrm{kH})} \quad$ dispersion relation $[\omega=\omega(\mathrm{k})]$

$$
\mathrm{c}=\frac{\omega}{\mathrm{k}}, \quad \therefore \mathrm{c}=\sqrt{\frac{\mathrm{g}}{\mathrm{k}} \tanh (\mathrm{kH})}
$$

Note: c, $\omega$ indep of amplitude a (a feature of linear waves).

Now consider the limiting cases of "deep-water" and "shallowwater" surface gravity waves.
"deep-water" condition: $\lambda \ll \mathrm{H}$ or $\frac{\mathrm{H}}{\lambda} \gg 1$ or $\mathrm{kH} \gg 1$
$\therefore \tanh (\mathrm{kH}) \approx 1$

Actually, $\tanh (\mathrm{kH}) \approx 1$ even for $\mathrm{H} / \lambda$ not too big:


So, in practice, have
"deep water" for kH > 1.75

So for deep water: $\omega_{\text {deep }}=\sqrt{\mathrm{gk}}$,

$$
c_{\text {deep }}=\sqrt{\frac{g}{k}}=\sqrt{\frac{g \lambda}{2 \pi}}
$$

$\therefore$ Longer waves have faster phase speeds. [No H dependence]

Consider a mixture of short and long waves in deep water.

After a while, waves sort themselves out (disperse):

superposition of short + long waves

short waves are slow pokes
long waves in front

When there's a storm way out at sea, the first waves to reach the shore are the long waves (low frequency waves).
"shallow-water" condition: $\lambda \gg \mathrm{H}$ or $\frac{\mathrm{H}}{\lambda} \ll 1$ or $\mathrm{kH} \ll 1$
$\therefore \tanh (\mathrm{kH})=\frac{\mathrm{e}^{\mathrm{kH}}-\mathrm{e}^{-\mathrm{kH}}}{\mathrm{e}^{\mathrm{kH}}+\mathrm{e}^{-\mathrm{kH}}}=\frac{(1+\mathrm{kH}+\ldots)-(1-\mathrm{kH}+\ldots)}{(1+\mathrm{kH}+\ldots)+(1-\mathrm{kH}+\ldots)}$

$$
=\frac{2 \mathrm{kH}+\ldots}{2+\ldots} \approx \mathrm{kH}
$$

$\therefore \omega_{\text {shallow }}=\sqrt{\mathrm{gk} \mathrm{kH}}=\mathrm{k} \sqrt{\mathrm{gH}}$
$\therefore \mathrm{c}_{\text {shallow }}=\frac{\omega_{\text {shallow }}}{\mathrm{k}}=\sqrt{\mathrm{gH}} \quad$ indep of $\mathrm{k}!$
So shallow-water waves are non-dispersive.
For shallow water waves, c $\downarrow$ as $\mathrm{H} \downarrow$
Consider wave crests approaching a beach obliquely:


Wave crests turn as they approach beach, end up $\|$ to beach. A case of wave refraction (bending of wave fronts in inhomogeneous media -- in this case variable $\mathrm{H}(\mathrm{x})$ ).
recall that for general surface gravity waves:

$$
\omega=\sqrt{\mathrm{gk} \tanh (\mathrm{kH})}, \quad \mathrm{c}=\sqrt{\frac{\mathrm{g}}{\mathrm{k}} \tanh (\mathrm{kH})}
$$

and that for "shallow water": $\mathrm{kH} \ll 1$ so we're led to

$$
\omega_{\text {shallow }}=\mathrm{k} \sqrt{\mathrm{gH}}, \quad \mathrm{c}_{\text {shallow }}=\sqrt{\mathrm{gH}}
$$

Now consider pressure in shallow water conditions:

$$
\begin{aligned}
\frac{\mathrm{p}_{\text {shallow }}}{\rho} & =\text { const }-\mathrm{gz}+\frac{\mathrm{a} \omega^{2} \approx \mathrm{k}^{2} \mathrm{gH}}{\mathrm{k}} \frac{\operatorname{cosh[\mathrm {k}(\mathrm {z}+\mathrm {H})]}{ }^{\approx 1}}{\sinh (\mathrm{kH}) \approx \mathrm{kH}} \cos (\mathrm{kx}-\omega \mathrm{t}) \\
& =\text { const }-\mathrm{gz}+\mathrm{ag} \cos (\mathrm{kx}-\omega \mathrm{t}) \\
& =\text { const }-\mathrm{g}(\mathrm{z}-\eta) \quad \text { Hydrostatic pressure distribution. }
\end{aligned}
$$

Now look at phase speed c for the general surface wave case (deep/shallow/whatever):

"deep" or "shallow" depends on $\lambda$ relative to H. Water that's 100 m deep is "deep" for $\lambda=10 \mathrm{~m}$ but "shallow" for $\lambda=1000 \mathrm{~m}$.

Derive streamfunction for surface gravity wave [recall this is a 2D incomp flow]

$$
\frac{\partial \psi}{\partial z}=u=\frac{\partial \phi}{\partial x}=a \omega \frac{\cosh [k(\mathrm{z}+\mathrm{H})]}{\sinh (\mathrm{kH})} \cos (\mathrm{kx}-\omega \mathrm{t})
$$

integrate w.r.t. z:
(1) $\quad \psi=\frac{\mathrm{a} \omega}{\mathrm{k}} \frac{\sinh [\mathrm{k}(\mathrm{z}+\mathrm{H})]}{\sinh (\mathrm{kH})} \cos (\mathrm{kx}-\omega \mathrm{t})+\mathrm{F}(\mathrm{x}, \mathrm{t})$

Similarly, $\frac{\partial \psi}{\partial \mathrm{x}}=-\mathrm{w}=\ldots \quad$ Integrate w.r.t. x , to get:
(2) $\quad \psi=\frac{\mathrm{a} \omega}{\mathrm{k}} \frac{\sinh [\mathrm{k}(\mathrm{z}+\mathrm{H})]}{\sinh (\mathrm{kH})} \cos (\mathrm{kx}-\omega \mathrm{t})+\mathrm{G}(\mathrm{z}, \mathrm{t})$
$F(x, t)=G(z, t)$ but $f^{n}$ of $x$ can't be a $f n$ of $z--$ so no $x$ or $z$ dependence. So $F(x, t)=G(z, t)=E(t)$. But $E(t)$ is irrelevant since $u$, w only care about spatial derivs of $\psi$. So take $E(t)=0$.

$$
\therefore \quad \psi=\frac{\mathrm{a} \omega}{\mathrm{k}} \frac{\sinh [\mathrm{k}(\mathrm{z}+\mathrm{H})]}{\sinh (\mathrm{kH})} \cos (\mathrm{kx}-\omega \mathrm{t})
$$

Graph streamlines ( $\psi=$ const $)$ at $\mathrm{t}=0$.

$$
\begin{aligned}
\psi=0 \text { for: } \mathrm{z}=-\mathrm{H} \text { and for: } & \underset{\downarrow}{\mathrm{k}} \mathrm{x}= \pm \frac{\pi}{2}, \pm \frac{3 \pi}{2}, \pm \frac{5 \pi}{2}, \ldots \\
& 2 \pi / \lambda \\
& \mathrm{x}= \pm \frac{\lambda}{4}, \pm \frac{3 \lambda}{4}, \pm \frac{5 \lambda}{4}, \ldots
\end{aligned}
$$


[Get dirn of flow (arrows) from soln for u or w , or consider: for pattern moving toward right, $\eta$ is rising to right of crest (so w>0 there) and $\eta$ is falling to left of crest (so $w<0$ there). Arrows on
bottom give sense of horiz conv/div needed to support this w field. Clearly parcel velocity differs from phase speed.].

## Group Velocity

Concept of group velocity is appropriate for many different types of waves (not just surface gravity waves).

Consider 2 waves of equal amplitude and slightly different frequency and wavelength moving in same direction:

$$
\begin{array}{ll}
\omega_{1}=\omega+\Delta \omega, & \mathrm{k}_{1}=\mathrm{k}+\Delta \mathrm{k} \\
\omega_{2}=\omega-\Delta \omega, & \mathrm{k}_{2}=\mathrm{k}-\Delta \mathrm{k}
\end{array}
$$

assume $\quad \frac{\Delta \omega}{\omega} \ll 1, \quad \frac{\Delta \mathrm{k}}{\mathrm{k}} \ll 1$
Because of dispersion relation, $\Delta \omega$ is related to $\Delta \mathrm{k}$.
Mean frequency is: $\frac{\omega_{1}+\omega_{2}}{2}=\frac{\omega+\Delta \omega+\omega-\Delta \omega}{2}=\omega$
Mean wavenumber is: $\frac{\mathrm{k}_{1}+\mathrm{k}_{2}}{2}=\ldots=\mathrm{k}$
Where the waves are in phase (or nearly so) they combine to form a wave of twice amplitude. Where they're out of phase, they kill each other off.

2 waves in phase:


2 waves out of phase:


$$
\begin{aligned}
& \eta=a \cos \left(k_{1} x-\omega_{1} t\right)+a \cos \left(k_{2} x-\omega_{2} t\right) \\
& \quad=a \cos (k x-\omega t+\Delta k x-\Delta \omega t)+a \cos (k x-\omega t-(\Delta k x-\Delta \omega t)) \\
& =a \cos (k x-\omega t) \cos (\Delta k x-\Delta \omega t)-a \sin (k x-\omega t) \sin (\Delta k x-\Delta \omega t) \\
& + \\
& \quad a \cos (k x-\omega t) \cos (\Delta k x-\Delta \omega t)+a \sin (k x-\omega t) \sin (\Delta k x-\Delta \omega t) \\
& \quad=2 a \cos (k x-\omega t) \cos (\Delta k x-\Delta \omega t)
\end{aligned}
$$

$$
\therefore \eta=\underset{\downarrow}{\mathrm{A}} \underset{\downarrow}{\cos (\mathrm{kx}-\omega \mathrm{t})} \quad \text { where } \mathrm{A} \equiv 2 \mathrm{a} \cos (\Delta \mathrm{kx}-\Delta \omega \mathrm{t})
$$

effective carrier wave (mean wave) amplitude

Effective amplitude $A$ is itself a wave with wavelength
$\lambda_{\text {amplitude }}=\frac{2 \pi}{\Delta \mathrm{k}} \gg \frac{2 \pi}{\mathrm{k}}=\lambda_{\text {carrier wave }}$
A propagates at speed $\frac{\Delta \omega}{\Delta \mathrm{k}}$ where $\Delta \omega$ is related to $\Delta \mathrm{k}$ by dispersion rel ${ }^{\mathrm{n}}$. For small $\Delta \mathrm{k}, \frac{\Delta \omega}{\Delta \mathrm{k}} \rightarrow \frac{\mathrm{d} \omega}{\mathrm{dk}}$. Define $\mathrm{c}_{\mathrm{g}} \equiv \frac{\mathrm{d} \omega}{\mathrm{dk}}$
or $\quad \overrightarrow{\mathrm{c}}_{\mathrm{g}} \equiv \frac{\mathrm{d} \omega}{\mathrm{dk}} \hat{\mathrm{i}} \quad$ Group velocity. A vector.
c is phase speed of crests [not a vector, see fig. 7.3 Kundu)
$c_{g}$ is speed of envelope of crests.


Energy is trapped between nodes $\therefore$ energy propagates at speed of nodes (speed of envelope), i.e. speed $\mathrm{c}_{\mathrm{g}}$, not phase speed c.

For deep-water sfc waves:

$$
\begin{aligned}
& \omega=\sqrt{\mathrm{gk}} \\
& \mathrm{c}=\sqrt{\frac{\mathrm{g}}{\mathrm{k}}} \\
& \mathrm{c}_{\mathrm{g}}=\frac{\mathrm{d} \omega}{\mathrm{dk}}=\frac{1}{2 \sqrt{\mathrm{k}}} \sqrt{\mathrm{~g}}
\end{aligned}
$$

$\therefore \quad \mathrm{c}_{\mathrm{g}}=\frac{1}{2} \mathrm{c} \quad$ [since $\mathrm{c}>\mathrm{c}_{\mathrm{g}}$, individual crests move through envelope, die at nodes]

For shallow water sfc waves:

$$
\begin{aligned}
& \omega=\mathrm{k} \sqrt{\mathrm{gH}} \\
& \mathrm{c}=\sqrt{\mathrm{gH}} \\
& c_{\mathrm{g}}=\frac{\mathrm{d} \omega}{\mathrm{dk}}=\sqrt{\mathrm{gH}} \\
\therefore \quad & \mathrm{c}_{\mathrm{g}}=\mathrm{c}
\end{aligned}
$$

