

Instability of continuously-stratified shear flow

Consider a base-state consisting of a unidirectional flow in the horizontal: $\vec{U} = U(z)\hat{i}$, density $\bar{\rho}(z)$ and pressure $\bar{p}(z)$. There is wind shear (vertical shear of horiz wind). If shear is strong enough can get instability (Kelvin-Helmholtz instability).

See handouts for examples.

Can consider 3-D plane wave disturbances of the form:

$$\phi = \hat{\phi}(z) e^{i(kx + ly) - \sigma t}$$

but it turns out that two-dimensional disturbances ($l=0$) are more unstable than 3-D disturbances. Specifically, Squire's Theorem states:

To each unstable 3-D disturbance there corresponds a more unstable 2-D one.

See proof in Kundu. Squire's Theorem is valid for viscous and inviscid flows though we'll only be working w/ inviscid flows.

Consider linearized Boussinesq eq^{ns} with 2-D

velocity $(U+u)\hat{i} + w\hat{k}$, pressure $\bar{p}+p$ ^{hydrostatic based on $\bar{\rho}$} and density $\bar{\rho}+\rho$. So u, p, ρ are perturbation quantities, deviations from the base-state.

x-comp eqⁿ of motion:

$$\frac{\partial u}{\partial t} + U \frac{\partial u}{\partial x} + w \frac{\partial U}{\partial z} = -\frac{1}{\rho_0} \frac{\partial p}{\partial x}$$

z-comp eqⁿ of motion:

$$\frac{\partial w}{\partial t} + U \frac{\partial w}{\partial x} = -\frac{g\rho}{\rho_0} - \frac{1}{\rho_0} \frac{\partial p}{\partial z}$$

where ρ_0 is a const reference density

incompressibility : $\frac{\partial u}{\partial x} + \frac{\partial w}{\partial z} = 0$
 for 2D (x,z) flow

Thermo : $\frac{\partial e}{\partial \tau} + U \frac{\partial e}{\partial x} - \frac{\rho_0 N^2}{g} w = 0$

where $N^2 \equiv -\frac{g}{\rho_0} \frac{d\rho}{dz}$ (Brunt-Väisälä frequency)

Since flow is 2-D and incompressible, can introduce a streamfunction ψ through:

$$u = \frac{\partial \psi}{\partial z}, \quad w = -\frac{\partial \psi}{\partial x}$$

Eg^{ns} of motion and thermo then become :

$$\frac{\partial^2 \psi}{\partial z \partial \tau} + U \frac{\partial^2 \psi}{\partial x \partial z} - \frac{\partial \psi}{\partial x} \frac{dU}{dz} = -\frac{1}{\rho_0} \frac{\partial p}{\partial x}$$

$$-\frac{\partial^2 \psi}{\partial x \partial \tau} - U \frac{\partial^2 \psi}{\partial x^2} = -g \frac{e}{\rho_0} - \frac{1}{\rho_0} \frac{\partial p}{\partial z}$$

$$\frac{\partial e}{\partial \tau} + U \frac{\partial e}{\partial x} + \rho_0 \frac{N^2}{g} \frac{\partial \psi}{\partial x} = 0$$

Coefficients are indep of x and τ (but not z)
 \therefore anticipate that spatially-wavy sol^{ns} are possible.

Seek sol^{ns} of form: $\psi = \hat{\psi}(z) e^{ik(x-c\tau)}$
 $p = \hat{p}(z) e^{ik(x-c\tau)}$
 $e = \hat{e}(z) e^{ik(x-c\tau)}$

where k is real and c is possibly complex ($c = c_r + i c_i$)

∴ eq^{ns} of motion and thermo become:

$$(1) (U-c) \frac{d\hat{\psi}}{dz} - \hat{\psi} \frac{dU}{dz} = -\frac{\hat{p}}{\rho_0}$$

$$(2) k^2(U-c)\hat{\psi} = -g\frac{\hat{e}}{\rho_0} - \frac{1}{\rho_0} \frac{d\hat{p}}{dz}$$

$$(3) (U-c)\hat{e} + \rho_0 \frac{N^2}{g} \hat{\psi} = 0$$

eliminate \hat{p} by taking $\frac{d}{dz}$ of (1):

$$\left(\frac{dU}{dz} \frac{d\hat{\psi}}{dz} \right) + (U-c) \frac{d^2\hat{\psi}}{dz^2} - \left(\frac{d\hat{\psi}}{dz} \frac{dU}{dz} \right) - \hat{\psi} \frac{d^2U}{dz^2} = \frac{1}{\rho_0} \frac{d\hat{p}}{dz}$$

cancel

$$\therefore (U-c) \frac{d^2\hat{\psi}}{dz^2} - \hat{\psi} \frac{d^2U}{dz^2} - k^2(U-c)\hat{\psi} = +g\frac{\hat{e}}{\rho_0}$$

now use (2) to eliminate \hat{e}

$$\therefore (U-c) \left(\frac{d^2\hat{\psi}}{dz^2} - k^2\hat{\psi} \right) - \hat{\psi} \frac{d^2U}{dz^2} + \frac{N^2}{U-c} \hat{\psi} = 0$$

→ Taylor-Goldstein eqⁿ

2nd order linear variable-coefficient c.d.e.

Governs the structure of 2-D inviscid disturbances of stratified shear flow.

recall that $\psi = \hat{\psi}(z) e^{ik(x-c\tau)}$

and $c = c_r + ic_i$

$$\begin{aligned} \therefore \psi &= \hat{\psi}(z) e^{ikx - ik(c_r + ic_i)\tau} \\ &= \hat{\psi}(z) e^{ik(x - c_r\tau) - i^2 k c_i \tau} \quad i^2 = -1 \\ &= \hat{\psi}(z) e^{ik(x - c_r\tau) + k c_i \tau} \\ &= \hat{\psi}(z) e^{ik(x - c_r\tau)} e^{k c_i \tau} \end{aligned}$$

So if $k c_i > 0$ we have instability.

Take complex conjugate of T.-G. eqⁿ:

$$(U - c^*) \left(\frac{d^2 \hat{\psi}^*}{dz^2} - k^2 \hat{\psi}^* \right) - \frac{d^2 U}{dz^2} \hat{\psi}^* + \frac{N^2}{U - c^*} \hat{\psi}^* = 0$$

This eqⁿ is the same as original T.-G. eqⁿ but with c replaced by c^* and $\hat{\psi}$ replaced by $\hat{\psi}^*$.

This means: If $\hat{\psi}$ is an eigenfunction w/ eigenvalue $c (= c_r + ic_i)$ then $\hat{\psi}^*$ is an eigenfunction w/ eigenvalue $c^* (= c_r - ic_i)$

So, for each decaying mode there is a corresponding amplifying mode. So if $c_i \neq 0$ the flow is unstable.

[Note: if the T.-G. eqⁿ had an "i" in it anywhere (apart from i in c) the above result would not hold].

So now we want to see what flow scenario gives us $c_i \neq 0$.

Change variables to:

$$\phi \equiv \frac{\psi}{(U-c)^{1/2}}$$

$$\therefore \psi = (U-c)^{1/2} \phi$$

$$\therefore \frac{d\psi}{dz} = (U-c)^{1/2} \frac{d\phi}{dz} + \frac{1}{2} \frac{dU}{dz} \frac{\phi}{(U-c)^{1/2}}$$

$$\therefore \frac{d^2\psi}{dz^2} = (U-c)^{1/2} \frac{d^2\phi}{dz^2} + \frac{1}{2} \frac{dU}{dz} \frac{d\phi}{dz} \frac{1}{(U-c)^{1/2}}$$

$$\frac{1}{2} \frac{dU}{dz} \frac{d\phi}{dz} \frac{1}{(U-c)^{1/2}} + \frac{1}{2} \frac{d^2U}{dz^2} \phi \frac{1}{(U-c)^{1/2}} - \frac{1}{4} \left(\frac{dU}{dz} \right)^2 \frac{\phi}{(U-c)^{3/2}}$$

combine

Plug into Taylor-Goldstein eqⁿ, get:

$$(U-c)^{3/2} \frac{d^2\phi}{dz^2} + (U-c)^{1/2} \frac{dU}{dz} \frac{d\phi}{dz} + (U-c)^{1/2} \frac{1}{2} \frac{d^2U}{dz^2} \phi$$

$$- \frac{1}{4} \frac{(dU/dz)^2 \phi}{(U-c)^{3/2}} - k^2 (U-c)^{3/2} \phi - (U-c)^{1/2} \frac{d^2U}{dz^2} \phi + \frac{N^2}{(U-c)^{1/2}} \phi = 0$$

combine

÷ by $(U-c)^{1/2}$

$$\underbrace{(U-c) \frac{d^2 \phi}{dz^2} + \frac{dU}{dz} \frac{d\phi}{dz}}_{\text{combine}} - \phi \left[\frac{1}{2} \frac{d^2 U}{dz^2} + k^2(U-c) + \frac{\frac{1}{4} \left(\frac{dU}{dz} \right)^2 - N^2}{U-c} \right] = 0$$

$$\frac{d}{dz} \left[(U-c) \frac{d\phi}{dz} \right] - \phi \left[\frac{1}{2} \frac{d^2 U}{dz^2} + k^2(U-c) + \frac{\frac{1}{4} \left(\frac{dU}{dz} \right)^2 - N^2}{U-c} \right] = 0$$

Mult by ϕ^* (complex conj-gate of ϕ) and integrate from $z=0$ to $z=d$. Boundary conditions: in a lab put impermeable plates at $z=0$ and $z=d$. Impermeability condⁿ:

$w(0) = 0$
 $w(d) = 0$

but $w = -\frac{\partial \psi}{\partial x}$ so impermeability becomes:

$\frac{\partial \psi}{\partial x}(0) = 0$ and $\frac{\partial \psi}{\partial x}(d) = 0$ or, since $\psi = \hat{\psi}(z) e^{ik(x-ct)}$
 $\frac{\partial \psi}{\partial x} = ik \hat{\psi} e^{ik(x-ct)}$

so $\hat{\psi}(0) = 0$ and $\hat{\psi}(d) = 0$ or, since $\phi \equiv \frac{\hat{\psi}}{(U-c)^{1/2}}$

so $\phi(0) = 0$ and $\phi(d) = 0$ now take complex conj

so $\phi^*(0) = 0$ and $\phi^*(d) = 0$

$$\int \phi^* \frac{d}{dz} \left[(U-c) \frac{d\phi}{dz} \right] dz - \int \phi^* \phi \left[k^2(U-c) + \frac{1}{2} \frac{d^2 U}{dz^2} + \frac{\frac{1}{4} \left(\frac{dU}{dz} \right)^2 - N^2}{U-c} \right] dz = 0$$

integrate by parts $\rightarrow \left[\phi^* (U-c) \frac{d\phi}{dz} \right]_0^d - \int \frac{d\phi^*}{dz} (U-c) \frac{d\phi}{dz} dz$
 This boundary term is 0!

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∴ get:

$$\begin{aligned}
 (\star) \quad - \int & \left(\left| \frac{d\phi}{dz} \right|^2 (V-c) + k^2 (V-c) |\phi|^2 + \frac{1}{2} \frac{d^2 V}{dz^2} |\phi|^2 \right. \\
 & \left. + \frac{\frac{1}{4} \left(\frac{dV}{dz} \right)^2 - N^2}{V-c} |\phi|^2 \right) dz = 0
 \end{aligned}$$

Note that $V-c = V-c_r - ic_i$

$$\begin{aligned}
 \text{and } \frac{1}{V-c} &= \frac{1}{V-c} \frac{V-c^*}{V-c^*} = \frac{1}{V-c_r - ic_i} \frac{V-c_r + ic_i}{V-c_r + ic_i} \\
 &= \frac{V-c_r + ic_i}{(V-c_r)^2 + c_i^2}
 \end{aligned}$$

$$\text{So } \text{Im}(V-c) = -c_i$$

$$\text{and } \text{Im}\left(\frac{1}{V-c}\right) = \frac{c_i}{(V-c_r)^2 + c_i^2}$$

Taking imaginary part of (\star) yields (careful with signs!):

$$c_i \int \left(\underbrace{\left(\left| \frac{d\phi}{dz} \right|^2 + k^2 |\phi|^2 \right)}_{\text{pos}} - \frac{\left(\frac{1}{4} \left(\frac{dV}{dz} \right)^2 - N^2 \right) |\phi|^2}{\underbrace{(V-c_r)^2 + c_i^2}_{\text{denominator is pos}}} \right) dz = 0$$

\uparrow $|\phi|^2$ is pos

So if $\frac{1}{4} \left(\frac{dV}{dz} \right)^2 - N^2 < 0$ then $c_i \int (\text{pos}) dz = 0$

so $c_i (\text{pos}) = 0$ which ~~means~~ can only be

true if $c_i = 0$ ∴ Stable case!

But if $\frac{1}{4} \left(\frac{dU}{dz} \right)^2 - N^2 > 0$ then

$$C_i \int ((pos) + (neg)) dz = 0$$

indeterminate case... we can't say if the flow is stable or unstable.

Gradient Richardson number $Ri \equiv \frac{N^2}{\left(\frac{dU}{dz} \right)^2}$

So if $Ri > \frac{1}{4}$ everywhere the flow is stable.

but if $Ri < \frac{1}{4}$ the flow might be unstable, but who knows...

So... $Ri < \frac{1}{4}$ is a necessary but not sufficient condⁿ for instability.

Note: In practice, $Ri < \frac{1}{4}$ is usually unstable.

Consider special case where $N^2 = 0$ (neutral stratification). Then T.-G. eqⁿ reduces to:

$$\frac{d^2 \hat{\psi}}{dz^2} - k^2 \hat{\psi} - \frac{d^2 U}{dz^2} \hat{\psi} = 0$$

Rayleigh's eqⁿ

This same eqⁿ (w/ y replacing z) also holds for perturbations in a flow sheared in y-dirⁿ, $U(y)$ because gravity ~~does not enter~~ The problem

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Rayleigh showed that a necessary criterion for instability of an inviscid and unstratified shear flow is that the base-state velocity have an inflection point.

Proof: Multiply Rayleigh's eqⁿ by $\hat{\psi}^*$ and integrate from 0 to d (where $w=0 \rightarrow$ so $\hat{\psi}=0$ so $\hat{\psi}^*=0$).

$$\int \hat{\psi}^* \frac{d^2 \hat{\psi}}{dz^2} dz - k^2 \int \hat{\psi}^* \hat{\psi} dz - \int \left(\frac{d^2 U / dz^2}{U - c} \right) \hat{\psi}^* \hat{\psi} dz = 0$$

\rightarrow integrate by parts, get $\left[\hat{\psi}^* \frac{d \hat{\psi}}{dz} \right]_0^d - \int \frac{d \hat{\psi}^*}{dz} \frac{d \hat{\psi}}{dz} dz$

This is 0 from the b.c.

Mult by -1, get

$$(A) \int \left| \frac{d \hat{\psi}}{dz} \right|^2 dz + k^2 \int |\hat{\psi}|^2 dz + \int \left(\frac{d^2 U}{dz^2} \right) \frac{|\hat{\psi}|^2}{U - c} dz = 0$$

recall that $\frac{1}{U - c} = \frac{U - c_r + i c_i}{(U - c_r)^2 + (c_i)^2}$ so the

imaginary part of above eqⁿ is:

$$c_i \int \frac{\frac{d^2 U}{dz^2}}{(U - c_r)^2 + (c_i)^2} |\hat{\psi}|^2 dz = 0$$

Suppose flow is unstable (so $c_i \neq 0$). Then

must have $\int \frac{\frac{d^2 U}{dz^2}}{(U - c_r)^2 + (c_i)^2} |\hat{\psi}|^2 dz = 0$

$\underbrace{\hspace{10em}}_{\text{pos}}$

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So $\frac{d^2U}{dz^2}$ must be pos and neg within the flow domain $\therefore \frac{d^2U}{dz^2}$ must be 0 (inflection point)

somewhere in interior. So an inflection point ~~is~~ in $U(z)$ within the flow domain is a Necessary condⁿ for instability (but it's not a sufficient condⁿ).

To get a stronger necessary condⁿ for instability, Fjortoft also considered the real part of (A). Regardless of whether c_i is 0 or not, the real part of (A) is:

$$\underbrace{\int \left| \frac{d\hat{\psi}}{dz} \right|^2 dz + k^2 \int |\hat{\psi}|^2 dz}_{\text{This is pos}} + \underbrace{\int \frac{\frac{d^2U}{dz^2} (U - c_r)}{(U - c_r)^2 + (c_i)^2} |\hat{\psi}|^2 dz}_{\therefore \text{This must be neg}} = 0$$

$$\therefore (B) \int \frac{\frac{d^2U}{dz^2} (U - c_r)}{(U - c_r)^2 + (c_i)^2} |\hat{\psi}|^2 dz < 0$$

Now again consider unstable case ($c_i \neq 0$). Multiply Rayleigh's inflection point criterion by $c_r - U_I$ where U_I is the base-state velocity at the inflection point.

$$\therefore \int \frac{\frac{d^2U}{dz^2} (c_r - U_I)}{(U - c_r)^2 + (c_i)^2} |\hat{\psi}|^2 dz = 0$$

Adding this result to the inequality (B), we get:

$$\int \frac{\frac{d^2U}{dz^2} (U - U_I)}{(U - c_r)^2 + (c_i)^2} |\hat{\psi}|^2 dz < 0$$

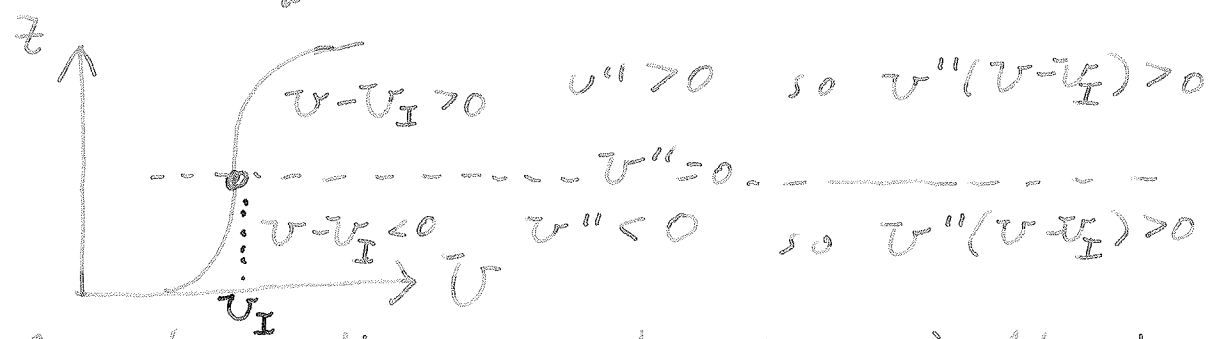
So in the unstable case must have :

$$\frac{d^2 U}{dz^2} (U - U_I) < 0 \text{ somewhere in the flow,}$$

It's a necessary condⁿ for instability. This is Fjortoft's Theorem.

Another way to state Fjortoft's Th^m : A necessary condⁿ for instability of inviscid shear flow is that the magnitude of the vorticity of the base-state U field has a maximum within the flow domain (i.e. not ^{good enough to have it} just on boundaries).

Rayleigh's inflection criterion implies that there be an extremum in the vorticity magnitude (max or min). Fjortoft refines (strengthens) the criterion by saying the extremum ~~is~~ must be a maximum.



In above diagram there is an inflection point but it's associated with a minimum in the magnitude of vorticity. Fjortoft's Th^m says: no instability in this case.

- Go through handout from Kundu on parallel shear flows.
- (a) stable (b) stable
 - (c) stable (d) Rayleigh: might be unstable; Fjortoft: stable
 - (e) Rayleigh + Fjortoft both: might be unstable (f) same as (e) (wins)